

FREEDM



SYSTEMS CENTER

A Co-Simulation Approach for modeling Transmission – Distribution – Microgrid - DER

Dr. Ning Lu

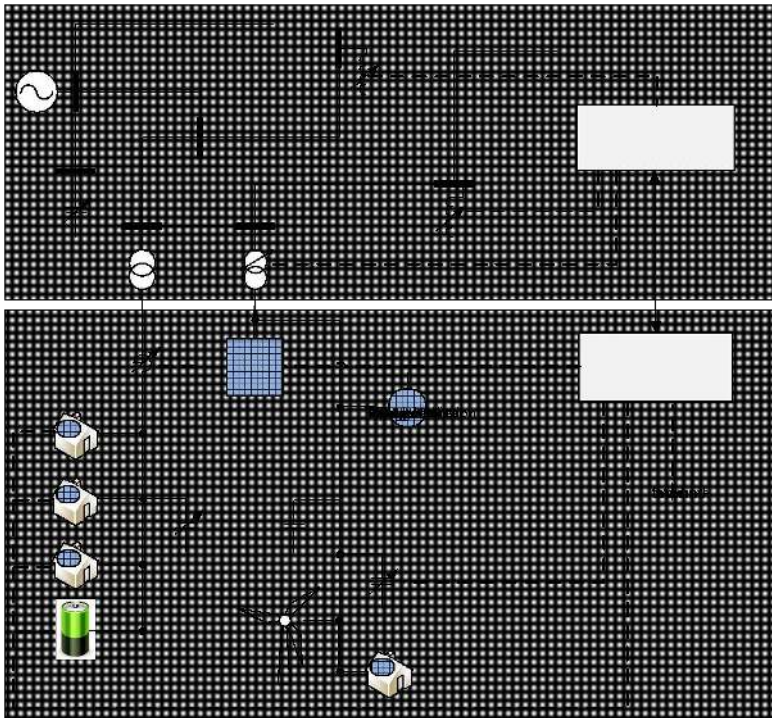
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GridWrx
Lab

Challenges

- Voltage regulation at subtransmission impedes solar penetration.
- Regulation devices are uncoordinated, unable to cope independently with system net load changes.



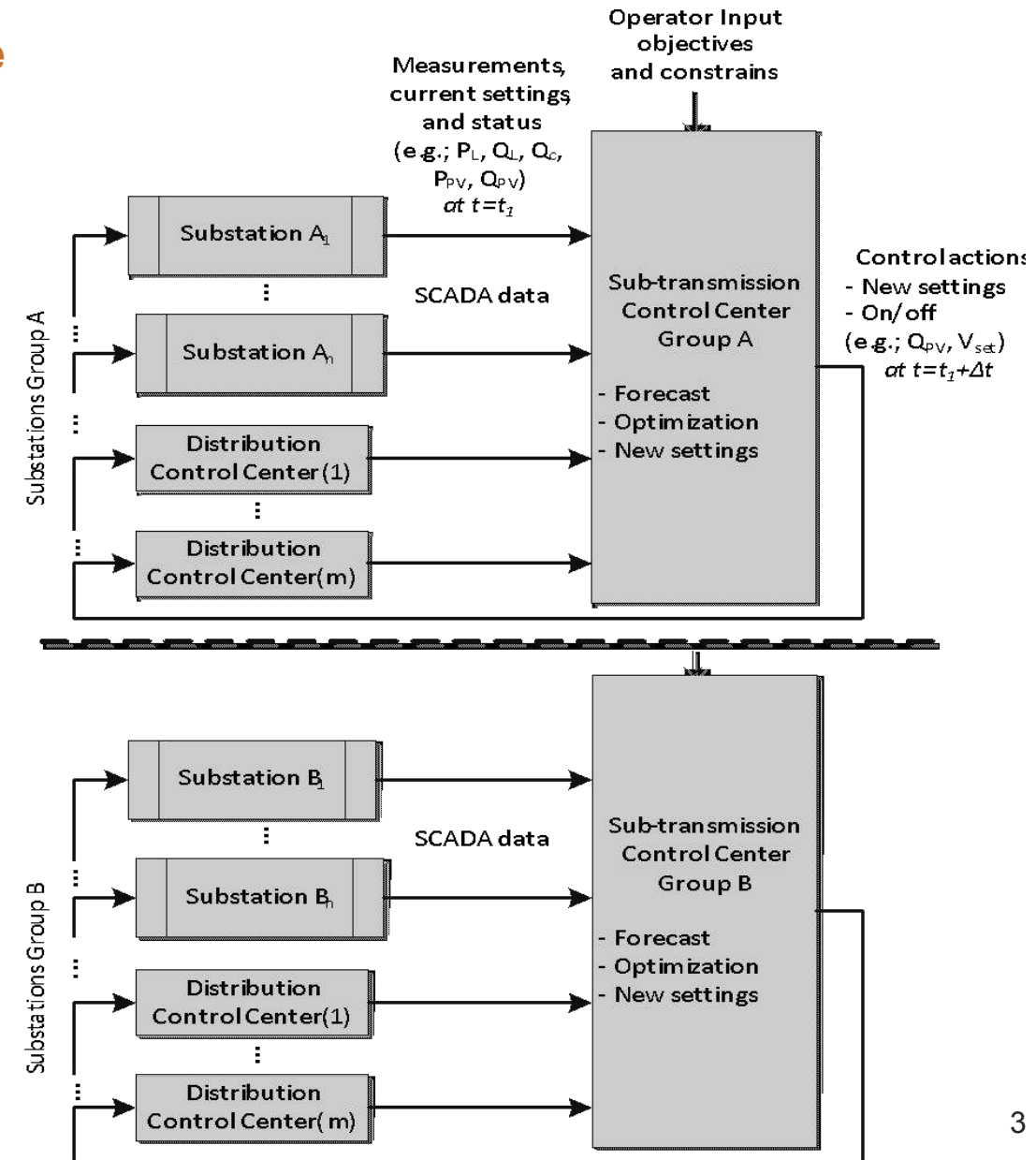
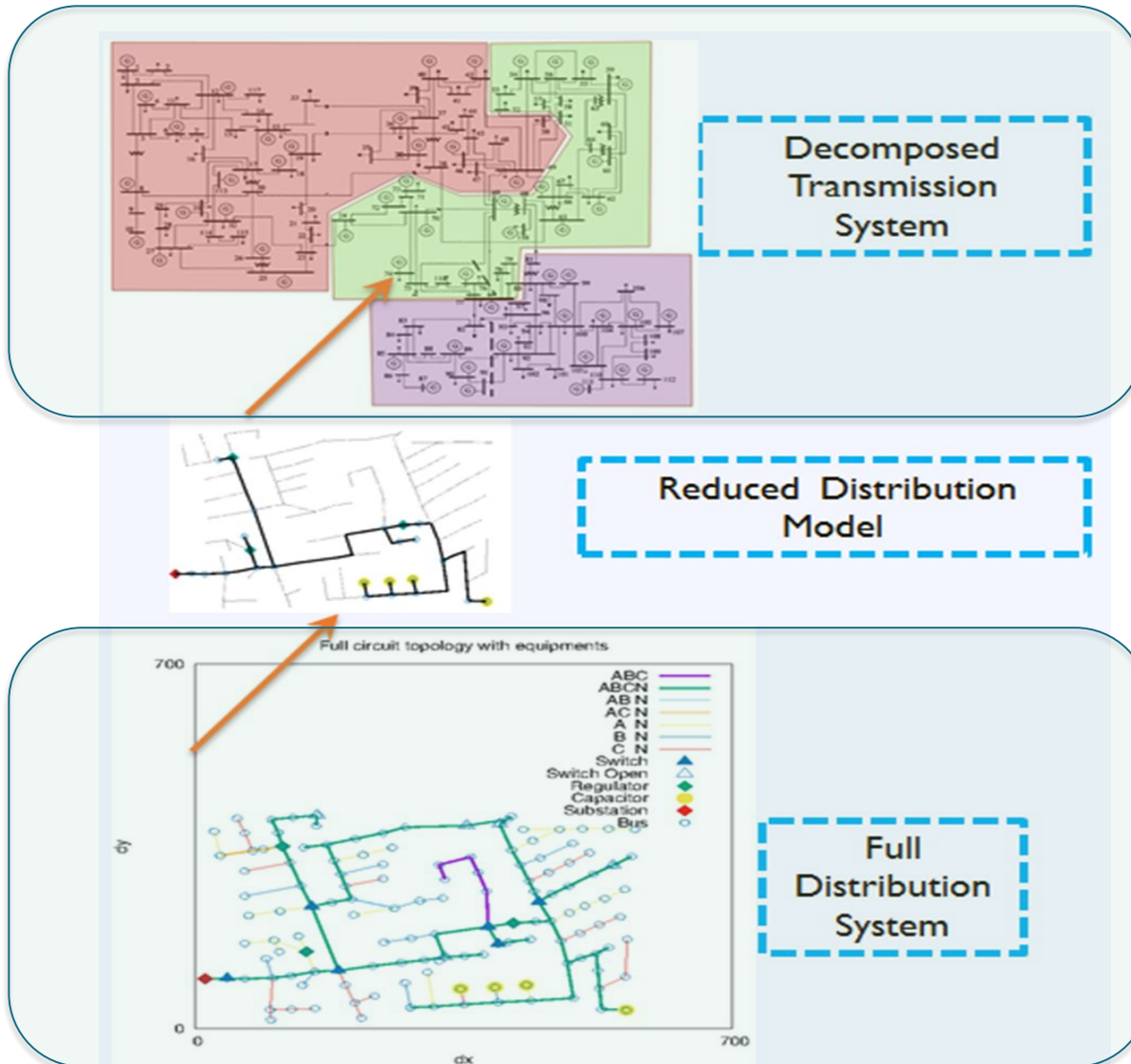
Solutions

- Develop a Coordinated Real-time Sub-Transmission Volt-Var Control Tool (CReST-VCT):
 - autonomous and supervisory control via flexible algorithm
 - co-optimization of distribution and subtransmission scales
- Develop an Optimal Future Sub-Transmission Volt-Var Planning Tool (OFuST-VPT):
 - Determine the size and location of new reactive compensation equipment needed to integrate high penetration of photovoltaic (PV) generation.
 - Consider the coordination achieved by CReST-VCT.

Outcomes

- High penetration of PV (100% of substation peak load, without violating voltage requirements)
 - Allow utilities to meet ANSI, IEEE, and NERC standards.
- Planning and operational support to utilities
 - Reduce interconnection approval time and cost.

Co-Optimization of Transmission and Distribution Voltage



Transmission AC Optimal Power Flow for Reactive Power Optimization

- **Objective function:** minimize weighted sum of

- load bus voltage deviation from target value
- transmission losses
- capacitor bank switching
- curtailment of controllable distributed solar output
- use of demand response

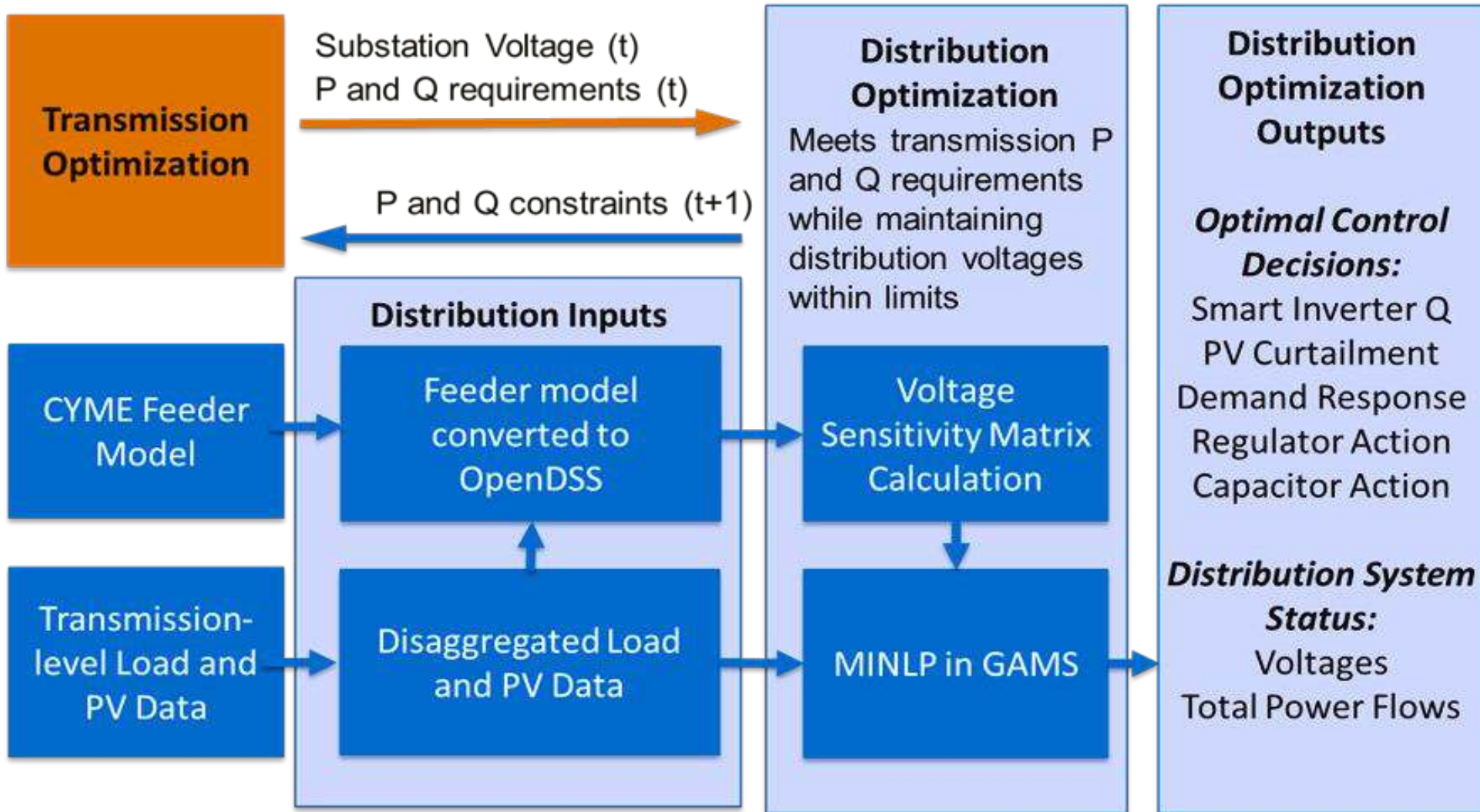
- **Output variables:**

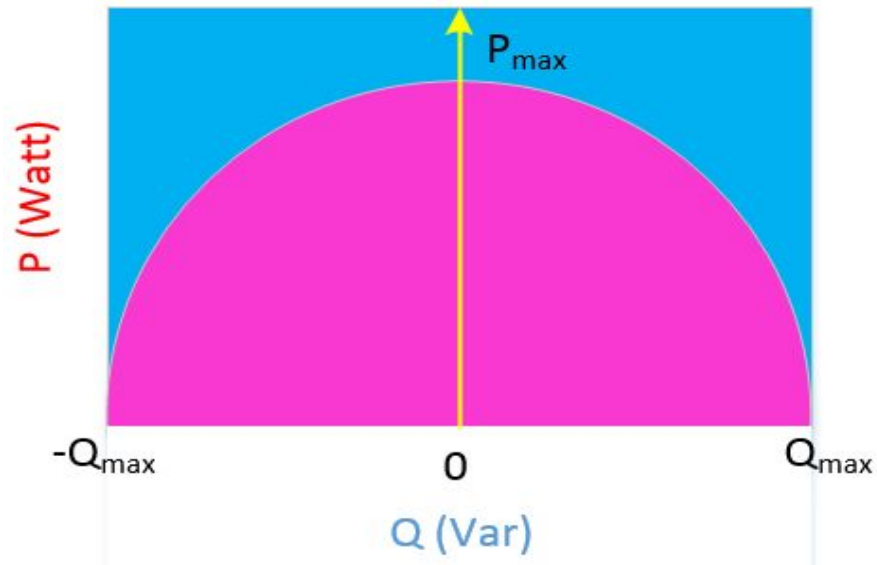
- reactive power requirements from distributed PV at each substation
- reactive power from capacitor banks at different substation
- real/reactive power required from demand response
- real power curtailment from PV

- **Constraints:**

Subject to

- AC power flow balance on each bus
- power plant scheduled real power, except on distributed slack
- power plant scheduled voltage and reactive power limits
- load real and reactive power
- distributed solar real power output
- bounds on reactive power from distributed solar



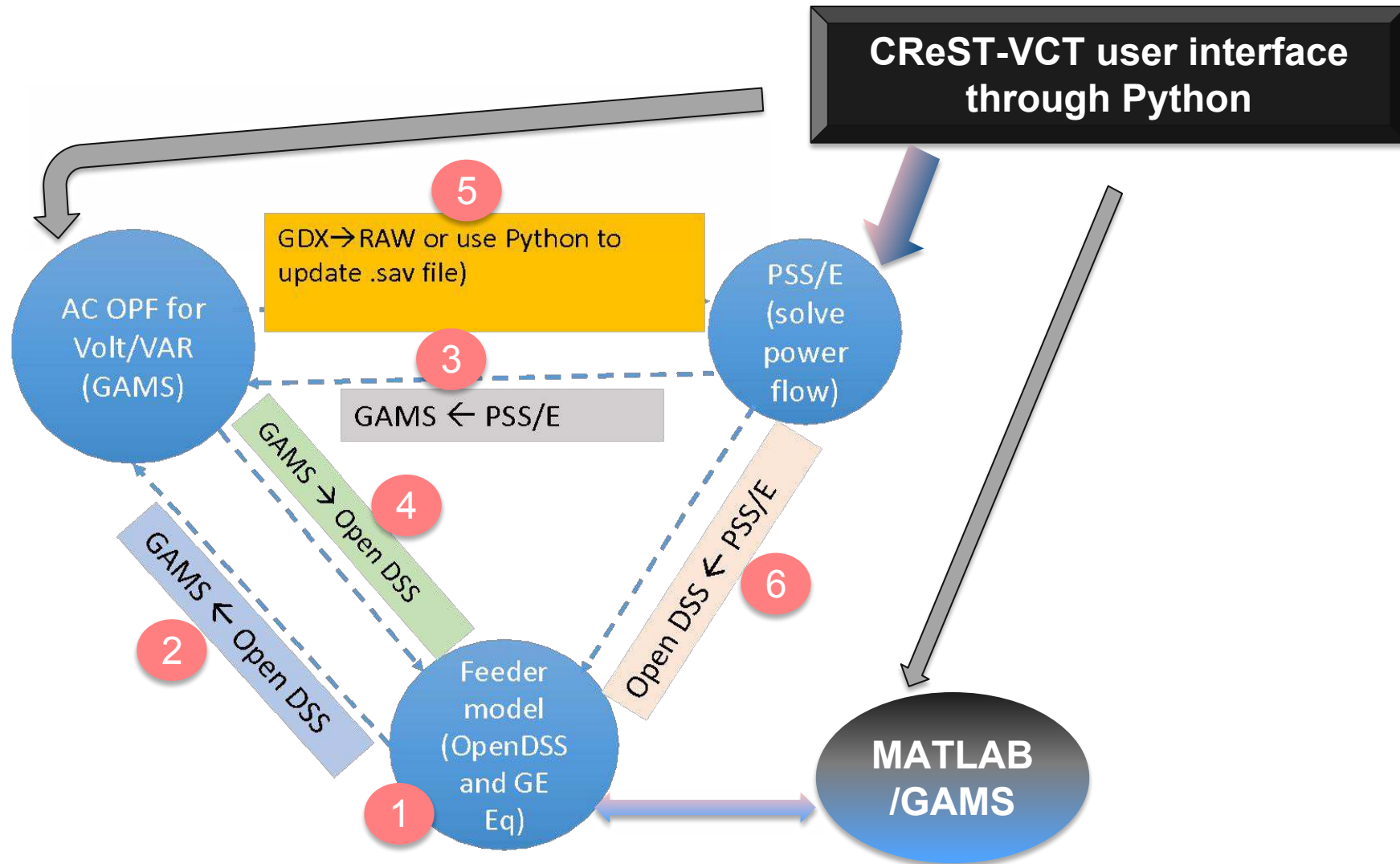


$$\frac{P^2}{P_{\max}^2} + \frac{Q^2}{Q_{\max}^2} \leq 1$$

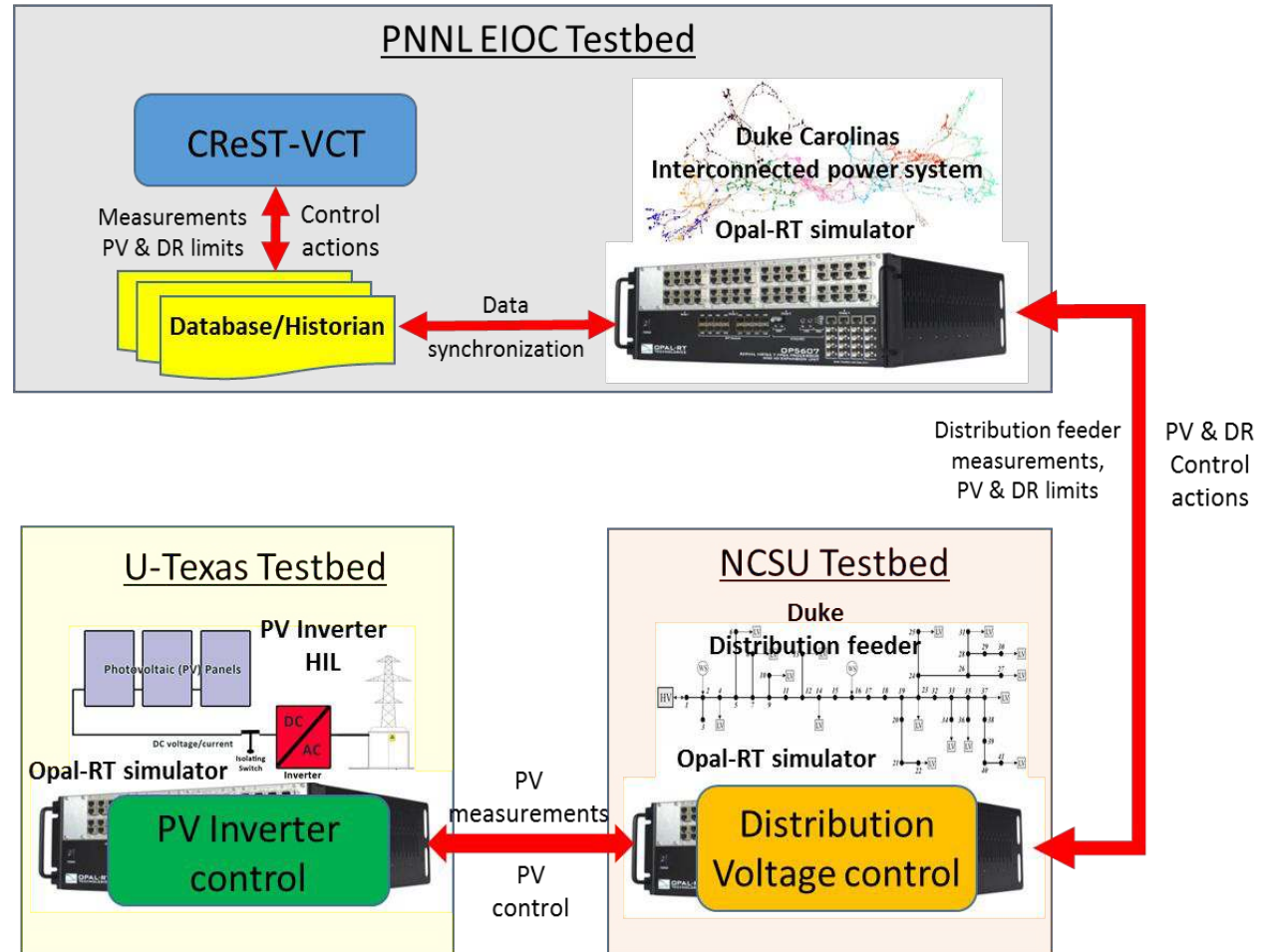
$$Q_{\max} = kP_{\max}$$

k is the **improved factor** for reactive power constraint, **1.1** for a normal **IGBT-based PV** inverter

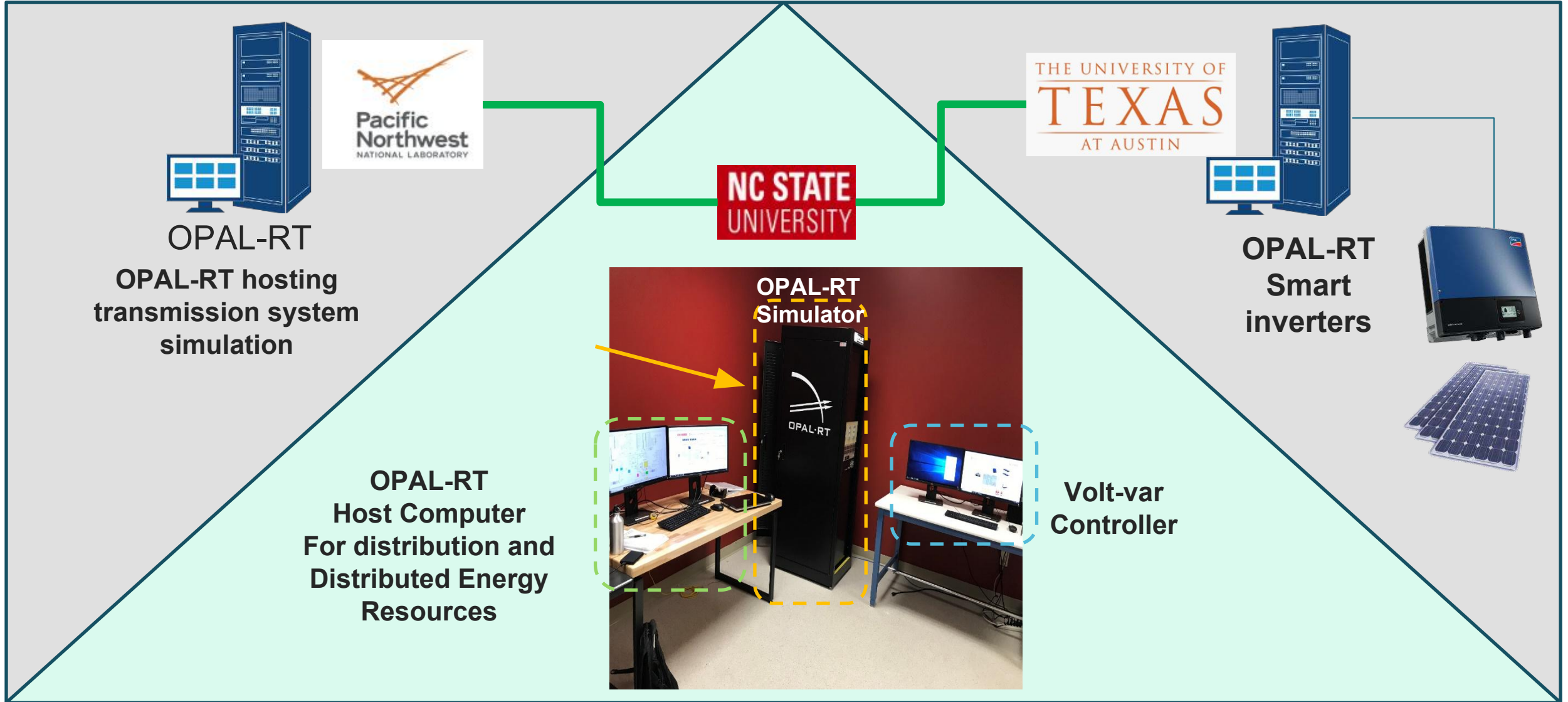
- *k* should be adjusted based on power electronics devices and modulation method.
- The *P/Q* constraint is also dependent on the filter and DC capacitor design.
- During nighttime when $P = 0$, reactive power injection results in additional power losses that might become an economic constraint.
- Three different reactive power regulation modes can be provided by the inverter (constant *Q*, constant Power Factor, and volt-var). We are using constant *Q* that is obtained from the optimization engine.



- Three hardware-in-the-loop (HIL) test systems have been developed to test the performance of
 - CReST-VCT developed at PNNL
 - Distribution voltage control based on PV control and demand response at NCSU
 - PV control with smart inverters at UT-Austin
- An integrated HIL test system have been developed using an Opal-RT facility at each site via a selected communication protocol.



- What is **real-time, hardware-in-the-loop** simulation?
 - **Real-time:** Simulation time elapsed is the actual time elapsed
 - Matlab simulation runs either faster or slower than the actual time
 - **Hardware-in-the-loop: A piece of hardware is connected to the simulation platform**
 - As the simulation time of a real-time HIL test system is the same as the actual time elapsed, one can connect hardware (e.g., controllers, relays, batteries, PV inverters) to it and test their performance
 - Model **communication** protocols
 - Consider **both the steady-state and the dynamic** simulations
- Value of using real-time HIL simulation
 - A cheaper, safer, scalable, and controlled way of developing new control systems, and testing equipment.



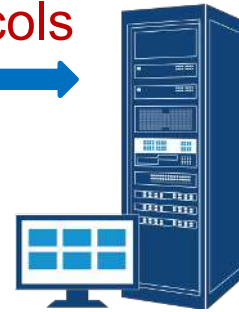


Communication Protocols

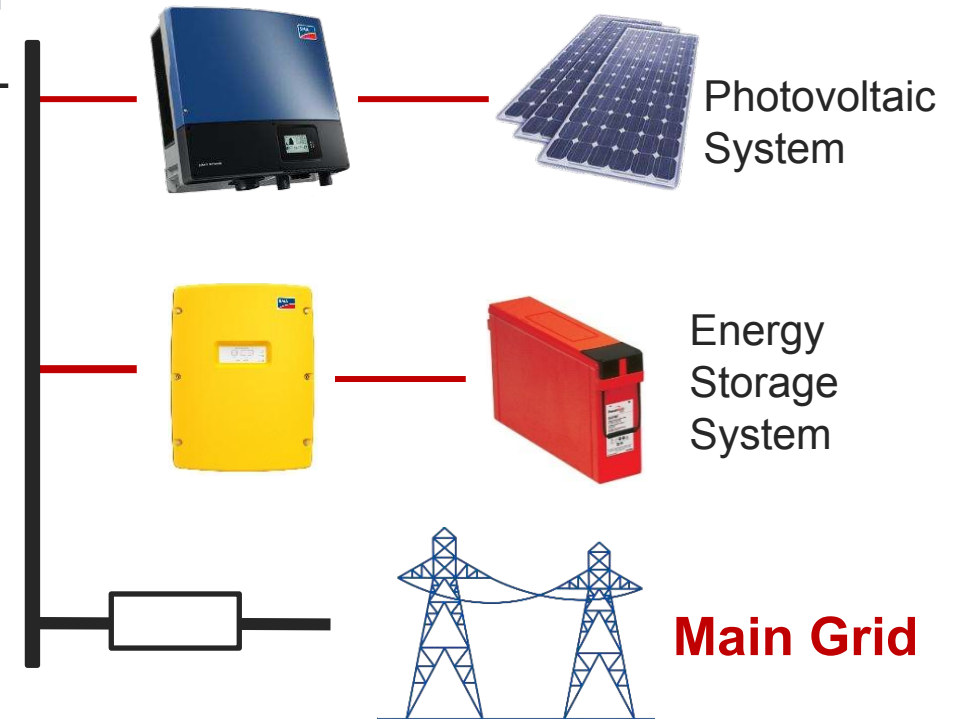
- Digital/analog I/O
- IEC 61850
- DNP3
- **Modbus**

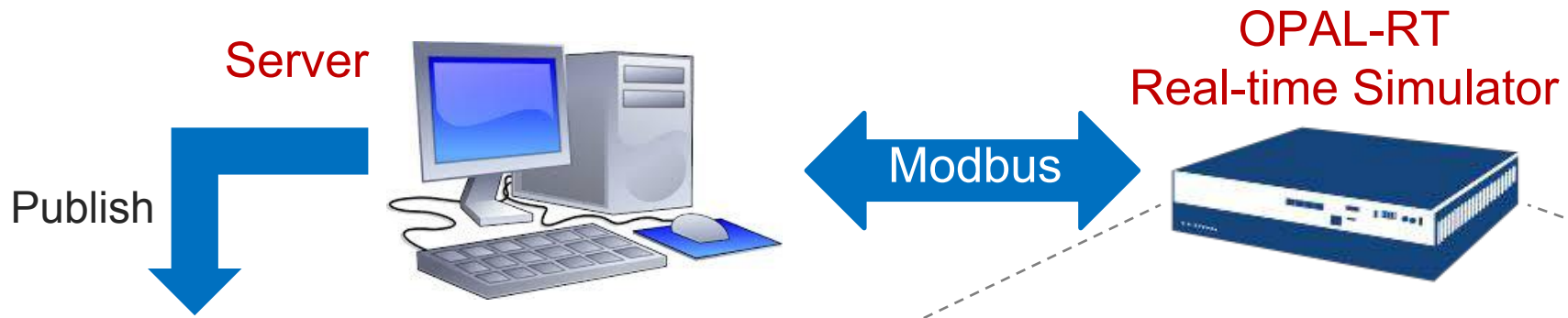
Remote Controller (Center)

- Control
 - Manual Control
 - Automated Control
 - Schedule and Dispatch
- Human–Machine Interface
 - SCADA System
 - Operation Dashboards



OPAL-RT

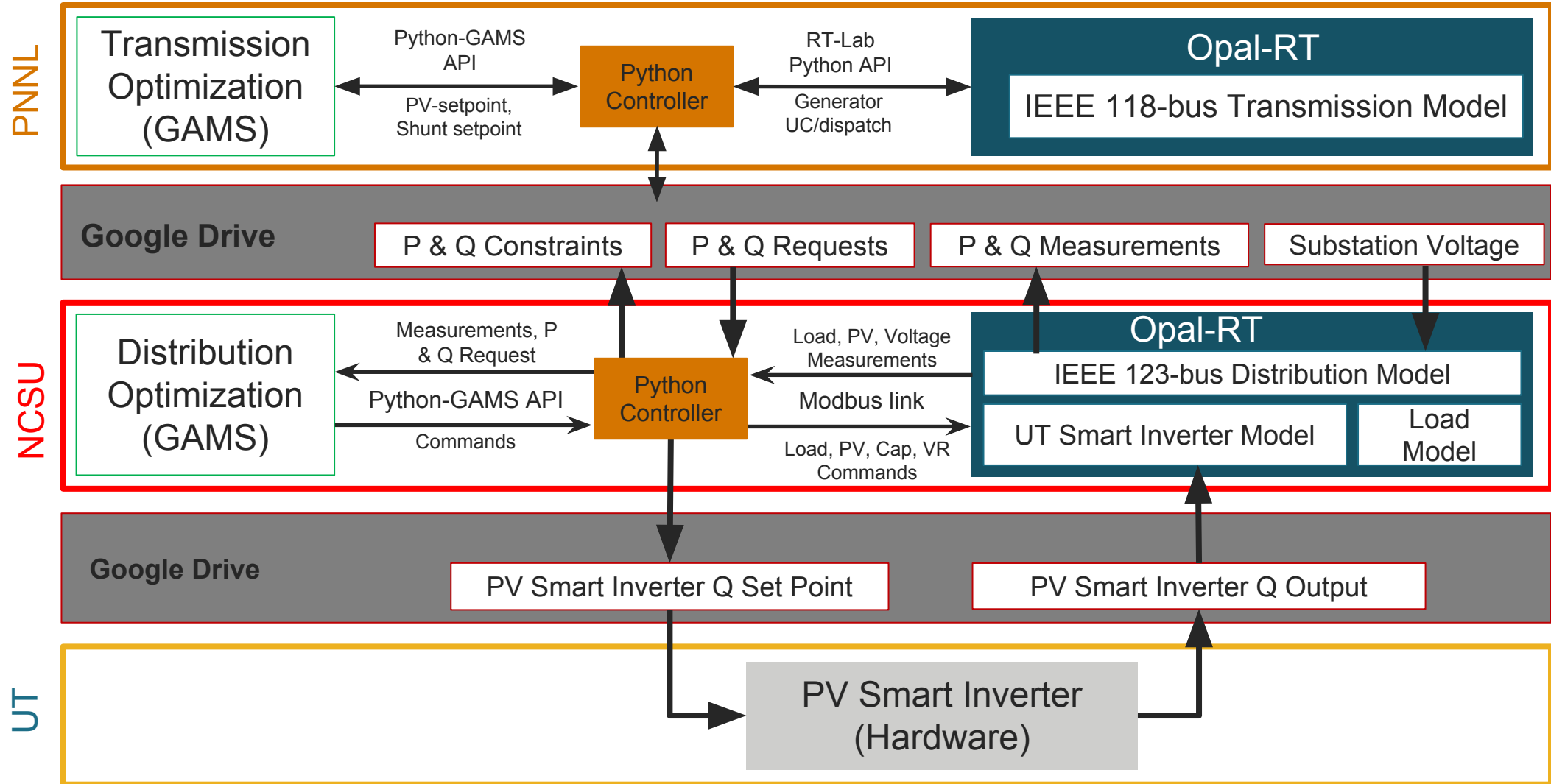


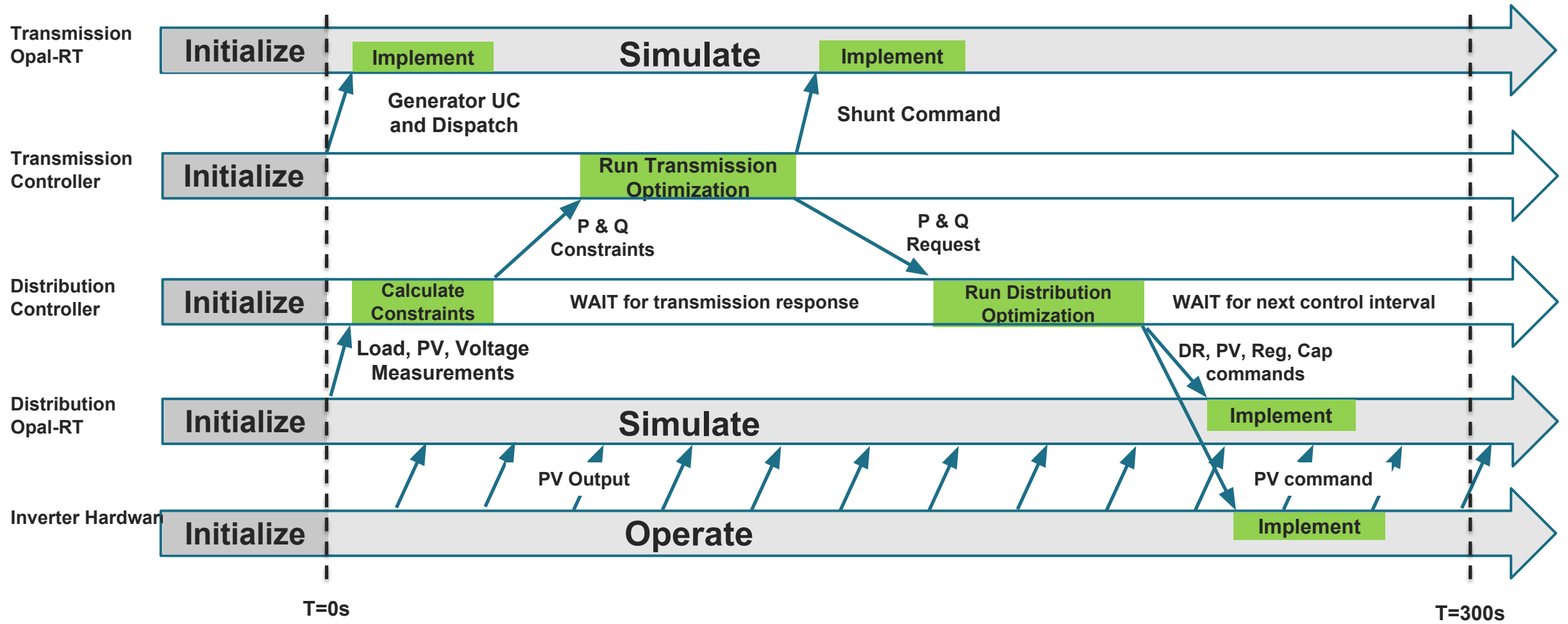


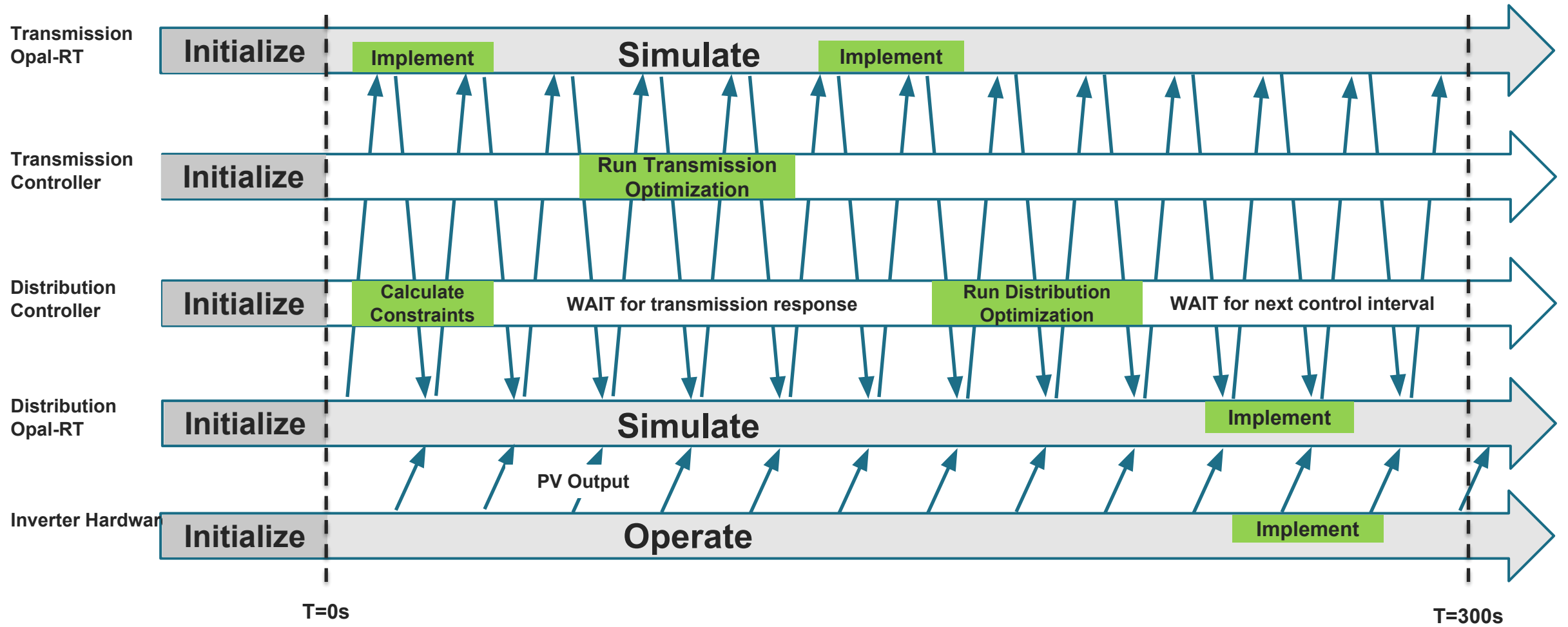
Web-based External Energy Management Interface

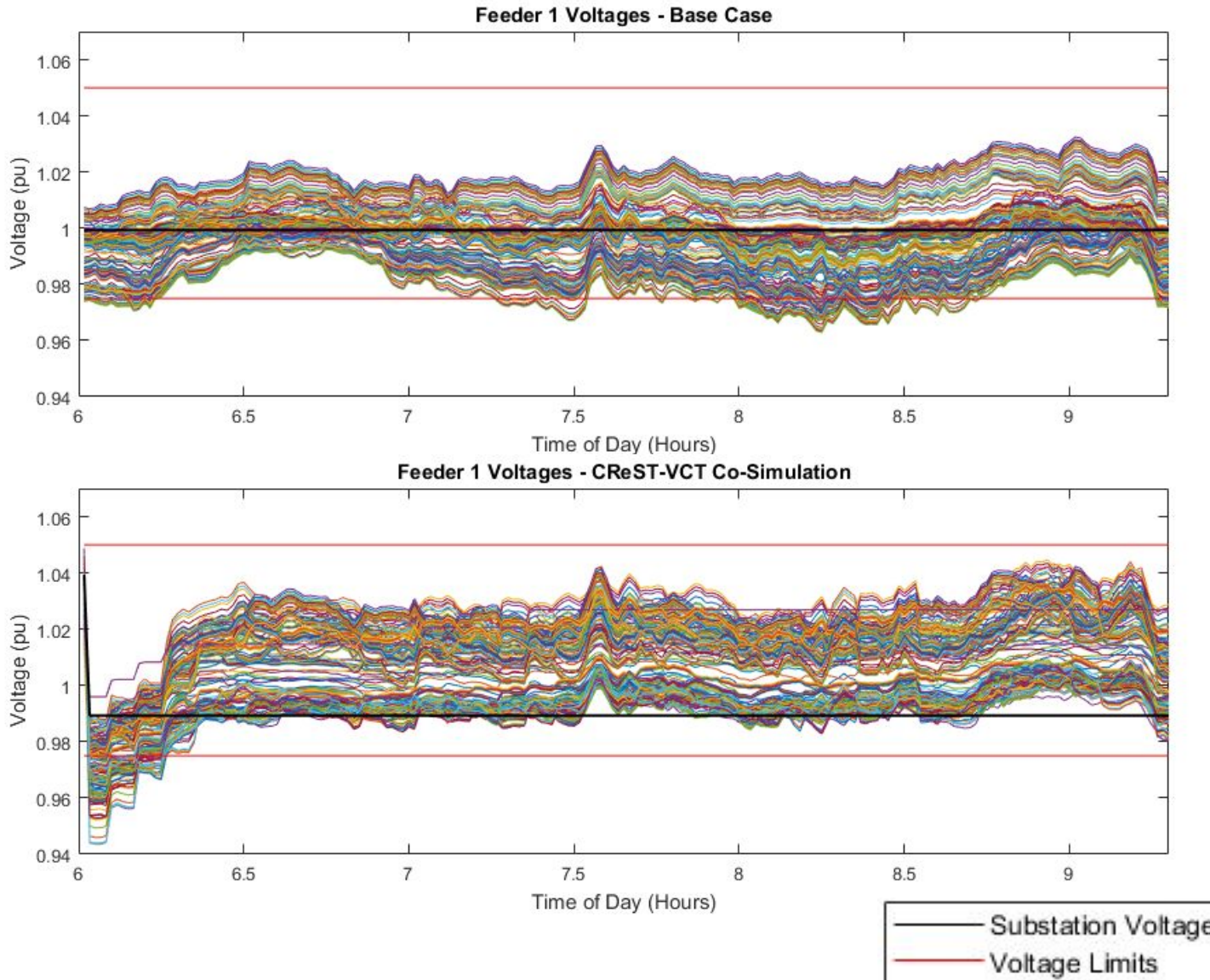
Hardware-in-the-loop Test Systems

	Status	Use Case	Simulink Models	Notes
1. PV and PV inverter	X	X	X	100μs
2. Battery and Battery Inverter	X	X	X	100μs
3. Distributed Generator Model	X	X	X	100μs
4. Load Model	X	X	X	100μs
5. System Integration Functions	X		X	
Use case 1: Grid connected to off-grid	X	X		
Use case 2: Microgrid operation	X	X		
Use case 3: Reconnect to the main grid	X	X		
6. Communication layer simulation	X			ModBus
7. Web-based interface	X			LabView
8. Transmission system (118-bus)	X			10 ms
9. Distribution system model (123-bus)	X			10 ms

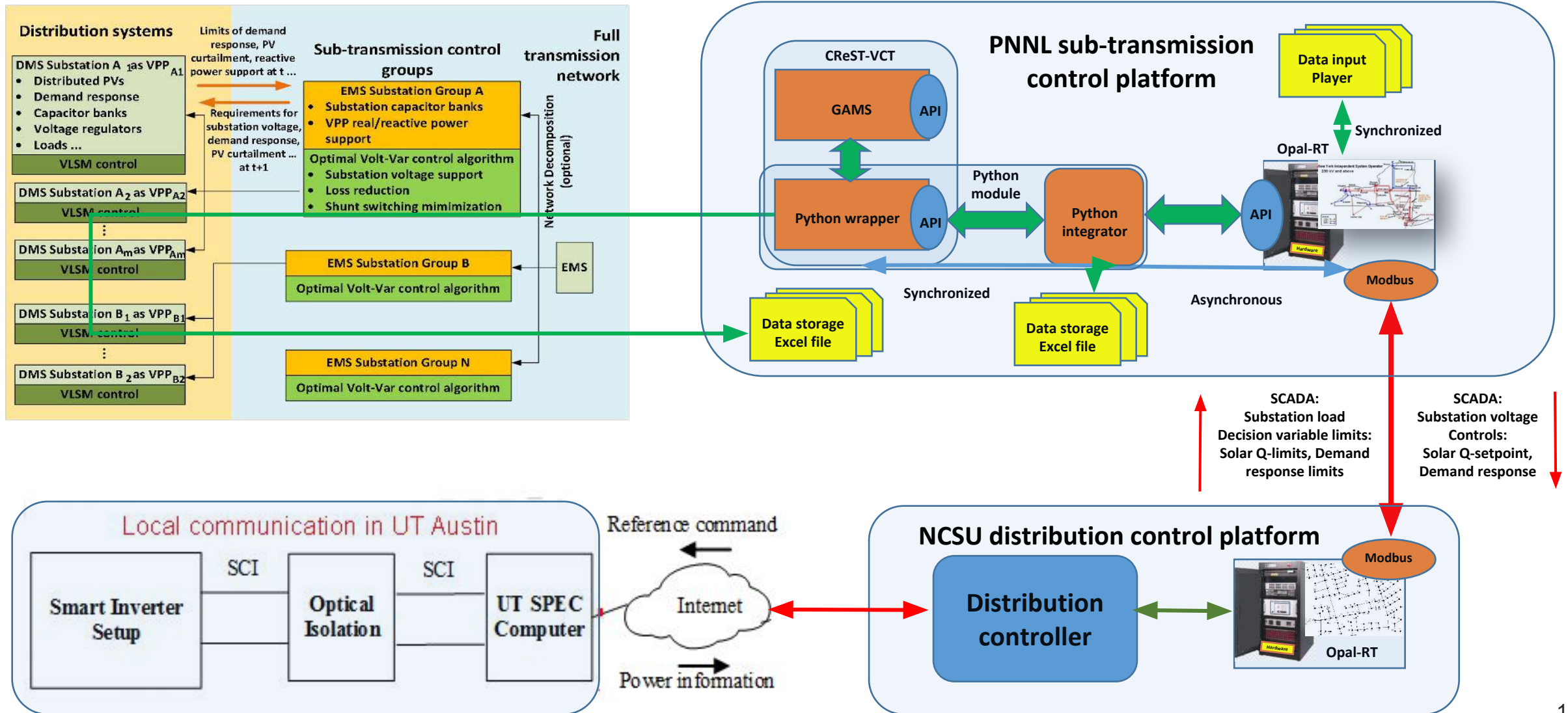






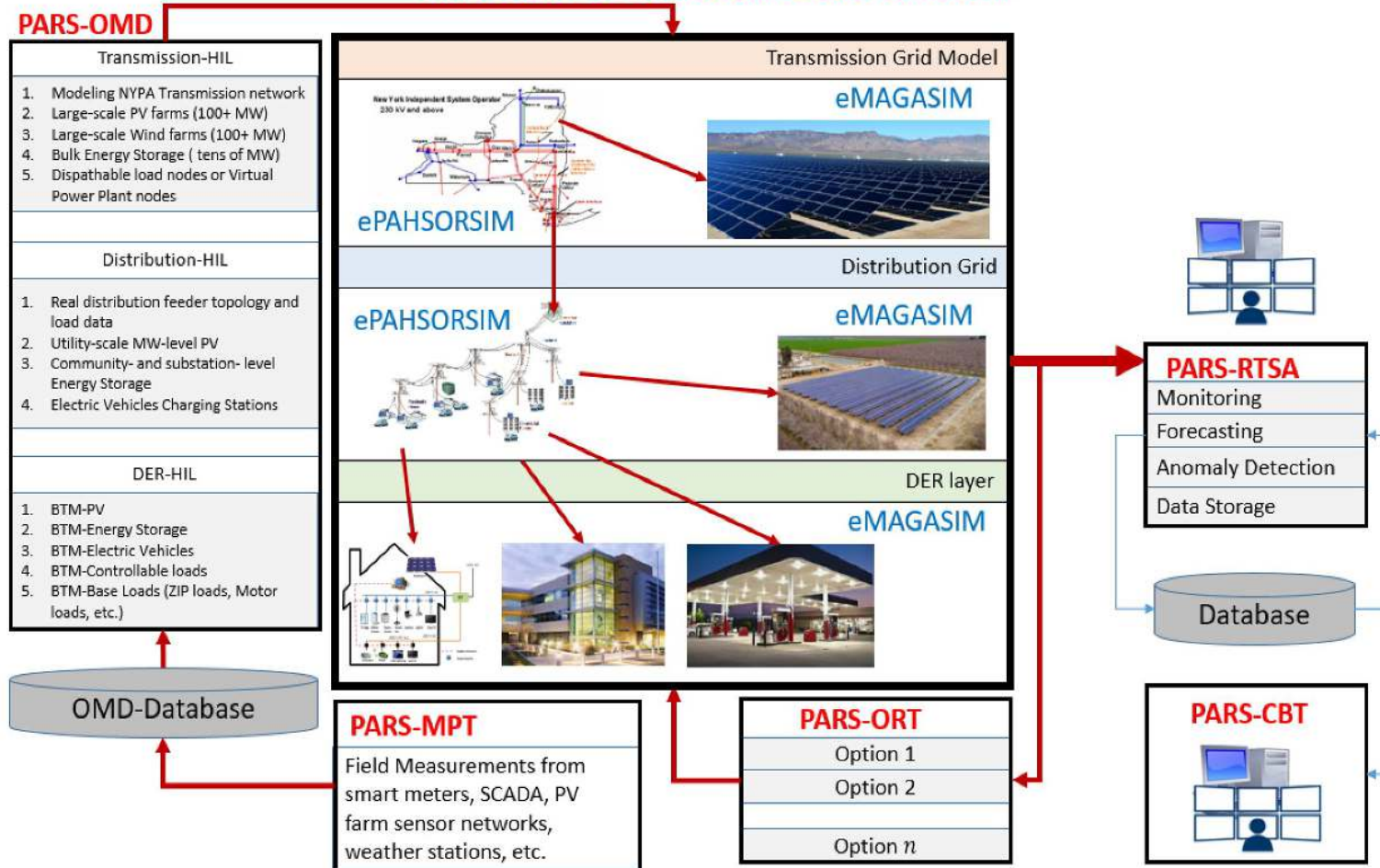


A universal co-simulation platform for multi-rate, multi-scale, multi-control mechanisms.



**Photovoltaic Analysis and Response Support (PARS) Platform
for Solar Situational Awareness and Resiliency Services**

An OPAL-RT based Real-time PARS Platform



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Co-PIs: David Lubkeman, Mesut Baran, Srdjan Lukic (North Carolina State University)

Key Participants:

- NCSU Clean Tech
- Pacific Northwest National Lab
- OPAL-RT Corporation
- New York Power Authority
- Strata Soalr
- Roanoke Electric Cooperative

Federal funds: \$3,180,000

Cost-share: \$798,000

Total: \$3,978,000



Enabling High Penetration of Distributed PV via Optimization of Subtransmission Voltage Regulation

Clean Energy States Alliance (CESA) Webinar
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